DIN W48×H48mm, W72×H36mm, W72×H72mm counter/timer

Upgraded functions

- Available to set 6 digits(0.00001 to 999999) prescale value (4digit : 0.001 to 9999)
- Built-in Modbus communication function(Communication model)
- Available to set the One-Shot output time in 10ms. (0.01sec. to 99.99sec.)
- Increase contact capacity to 5A(CTS, CTM Series)
- Available to set Count Start Point.(Initial value)
- Improved to select memory protection function in the indicator
- Added BATCH counter function(CTM Series)
- Added Counter Up-1 / Up-2 / Down-1 / Down-2 input modes
- Added Counter TOTAL / HOLD operation modes in the indicator
- Added Timer TOTAL / HOLD / On Time Display operation modes in the indicator
- Added Timer INT2 / NFD / NFD.1 / INTG output modes
- Added Timer range 999.999s / 9999m59 / 99999.9h

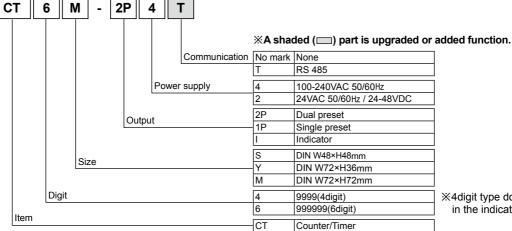
Please read "Caution for your safety" in operation manual before using.

DAQMaster(integrated device management program)

- DAQMaster is a integrated device management program for convenient management of parameters and multiple device data monitoring.
- Visit our website (www.autonics.com) to download user manual and integrated device management program.

Item	Minimum requirements
Sustem	IBM PC compatible computer with Intel Pentium
System	III or above
Operating system	Microsoft Windows 98/NT/XP/Vista/7
Memory	256MB or more
Hard disk	More than 1GB of free hard disk space
VGA	1024×768 or higher resolution display
Others	RS-232 serial port(9-pin), USB port

Ordering information



%4digit type does not exist in the indicator type.



Upgrade

< DAQMaster screen >

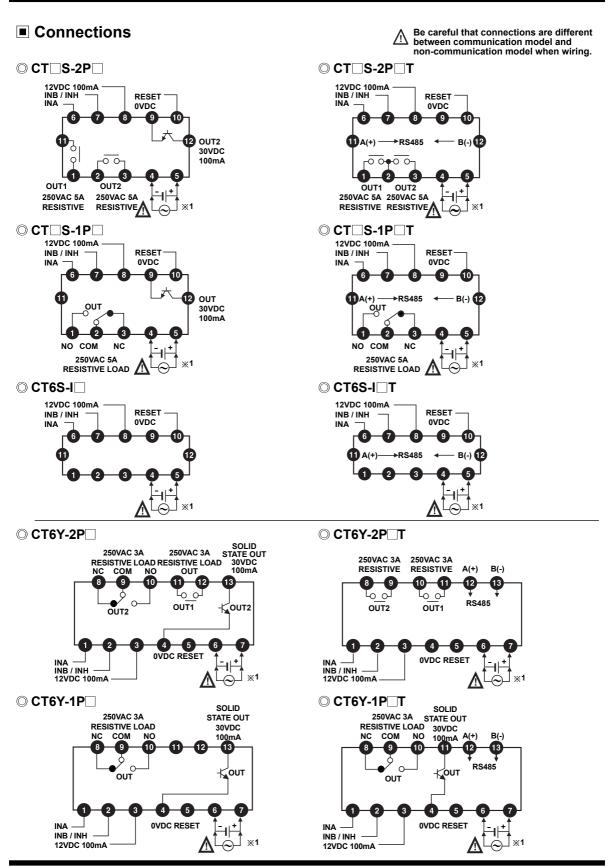


Specifications

eries			CTS		CTY	СТМ	electr	
Digit			4	6	6	6		
	Dual	Preset	CT4S-2P	CT6S-2P	CT6Y-2P	CT6M-2P	(B) Fiber	
Model	Single	e Preset	CT4S-1P	CT6S-1P	CT6Y-1P	CT6M-1P	optic	
	Single	e Preset		CT6S-1	CT6Y-1	CT6M-1	Sense	
Digit Size	<u> </u>	e Preset	11mm	10mm	10mm	13mm	(C)	
Size		e Preset	8mm	7mm	7mm	9mm	Door	
Power	<u> </u>	e Preset	100-240VAC 50/60					
Supply		e Preset	24VAC 50/60Hz / 2				(D)	
Allowable volt				d voltage(AC Power ty	vpe)		Proxi	
Power	Single	Preset	Max. 12VA	<u> </u>				
consumption			AC: Max. 10VA / D		40		(E)	
NA/INB Max	r			Ocps / 1kcps / 5kcps	TUKCPS		Press	
Min. input	Coun	ter	Reset signal : Sele	ctable Tms, 20ms				
signal width	Timer			Selectable 1ms, 20m		INA, INH, RESET, INHIBIT, BATCH RESET : Selectable 1ms, 20ms	(F) Rotar	
nput			Selectable voltage [Voltage input] Inpu [No-voltage input]	input or No-voltage in ut impedance is 5.4kΩ Short-circuit impedance	put , 'H' level : 5-30VDC, 'L' level : (æ : Max. 1kΩ, Residual voltage	D-2VDC : Max. 2VDC	encod	
One-shot out	put		Count, timer : Sele	ctable 0.01s to 99.99s	3		(G) Conn	
	With-	Contact output	Dual preset : SPS Single preset : SPI	[(1a) 2EA DT(1c) 1EA	Dual preset : SPST(1a) 1E Single preset : SPDT(1c) 1	A, SPDT(1c) 1EA EA	Sock	
	out com.	Solid state output	• ·	<u> </u>		Dual preset:3NPN open collector Single preset:2NPN open collector	(H) Temp contro	
Control	With-	Contact output	Dual preset : SPS Single preset : SPI	[(1a)2EA DT(1c)1EA		Dual preset: SPST(1a), SPDT(1c) Single preset: SPDT(1c)	(I)	
	out com.	Solid state output	—		Dual preset: - Single preset:1NPN open coll	Dual preset:2NPN open collector Single preset:2NPN open collector	SSR/ Powe contr	
	With-	Contact output	250VAC 5A resistiv	ve load	250VAC 3A resistive load	250VAC 5A resistive load	(J) Coun	
com. Solid state output 30VDC Max. 100mA Max.					Courr			
External sens		ver	12VDC ±10%, 100				(K)	
Memory reter	1		10years(When usi	ng non-volatile semico	onductor memory type)		Time	
		at error	-					
Timer	SET e	-	Power ON Start : Max. ±0.01% ±0.05 sec Signal Start : Max. ±0.01% ±0.03 sec					
	<u> </u>	ge error						
Insulation res		erature error	Min. 100MΩ(500V	DC Maggar)				
Dielectric stre		с	2,000VAC 50/60Hz				(M) Tach	
Noise strengt		Power)			:1µs) by the noise simulator		Spee mete	
- · · ·	Mech				55(for 1 min.)Hz in each of X, Y	Z directions for 1 hour		
Vibration		nction			5Hz(for 1 min.) in each of X, Y,		(N) Displ	
	Mech			DG) in each of X, Y, Z			unit	
Shock		nction		DG) in each of X, Y, Z				
Relay	Mech		Min. 10,000,000 or				(O) Sens	
_ife cycle	Electi			Min. 10,000 operations				
Protection								
	Ambi	ent erature	-10 to 55°C, storag	e : -25 to 65°C			(P) Switc mode	
Environment	Ambio	ent	35 to 85%RH, stor	age : 35 to 85%RH			(Q) Stepp	
Approval			(E : 91) us				moto	
Unit weight			Approx. 159g		Approx. 149g	Approx. 253g	Driver	
			proprion. 1009		pippion. 1709	1, ippion. 2009	(R)	

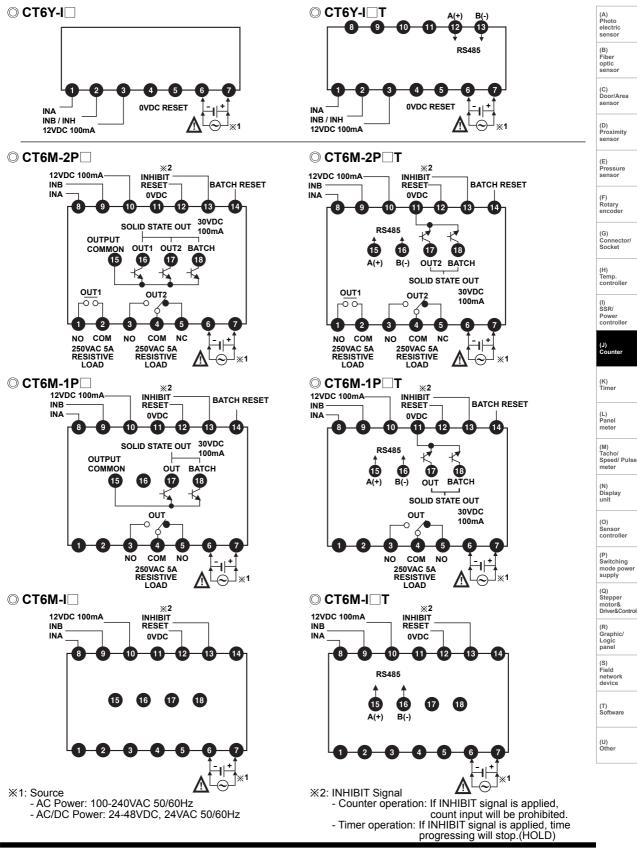
Communication specification

	cation specification	(S) Field
Protocol	Modbus RTU(16bit CRC)	network
Connection method	RS485	device
Application standard	Compliance with EIA RS485	
Number of connections	31, it is available to set address 1 to 127	(T) Software
Communication method	Half Duplex	
Synchronous method	Asynchronous	
Communication distance	within max. 800meter	(U) Other
Communication speed	2,400/4,800/9,600/19,200/38,400bps(Factory default : 9,600bps)	ouloi
Response waiting time	5 to 99ms(Factory default : 20ms)	
Start bit	1bit(Fixed)	
Data bit	8bits(Fixed)	
Parity bit	None, Even, Odd(Factory default : None)	
Stop bit	1, 2bit(Factory default : 2bit)	

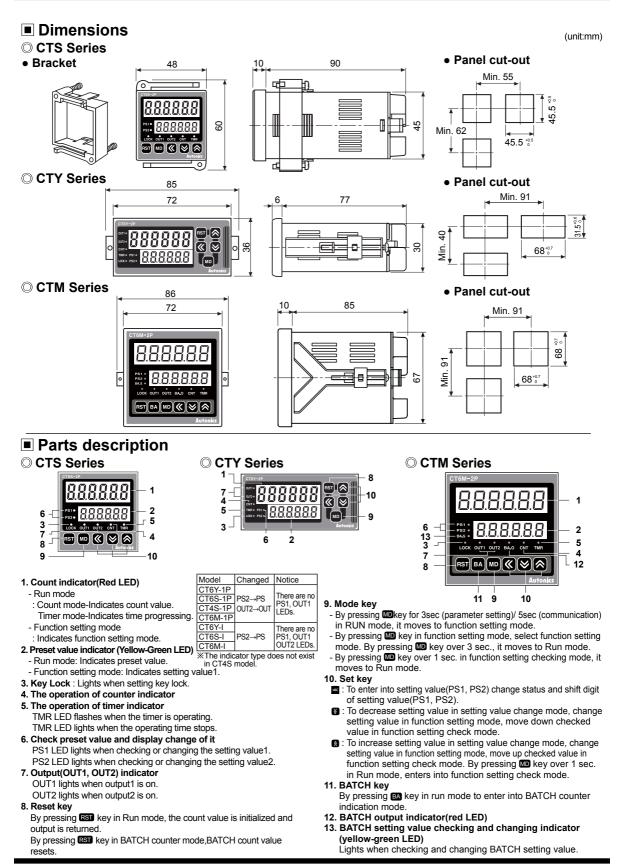


Autonics

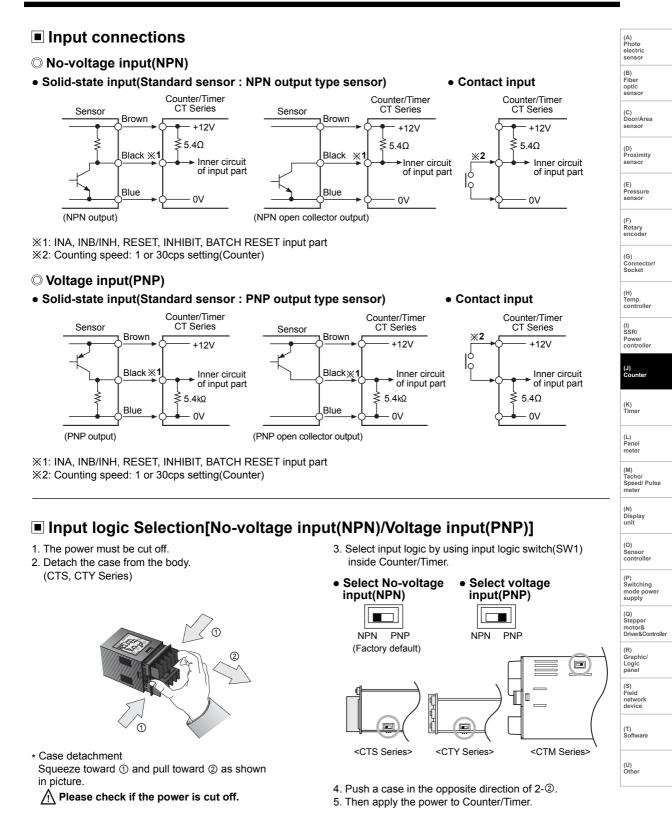
Programmable Counter/Timer



Autonics

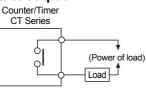


Autonics



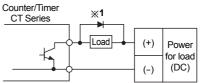
Output connections

○ Contact output



XUse proper load not to exceed the capacity.

○ Solid-state output



Use proper load and power for load not to excess ON/OFF capacity(30VDC Max. 100mA max.) of solid state output.
 Be sure not to apply reverse polarity of power.

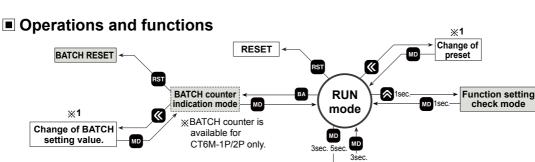
%1: When use inductive load(Relay etc), surge absorber (Diode, varistor etc) must be connected between both sides of the load.

	-actory default	
	Parameter	Factory default
	Input mode (i n)	UP/Down-C (IJơ-C)
	Output mode (aUE.ā)	F (F)
	CPS (EP5)	30cps (∃□)
	Indication mode (indicator type)(d5P.ñ)	TOTAL (Lot RL)
	OUT2 output time (oUE2)	Hold (Hold)
	OUT1 output time (oUE.1)	100ms (00.10)
Iter	Decimal point (dP)	
Counter	Min. reset time (r 5 b)	20ms (20)
0	Input logic (5/ 5)	NPN (۱۳۱)
	Prescale decimal point (5 ^{[.dP})	6digit type :, 4digit type :
	Prescale value (551)	6digit type: 1.00000 , 4digit type: 1.000
	Start Point setting (5٤٢٤)	00000
	Counting memory (dRER)	Clear (5Lr)
	Lock key (LoCY)	Lock off (L.oFF)
	Preset value 1 (PS1)	1000 (000)
	Preset value 2 (PS2)	5000 (5000)
	Time range (Holls / Til n / SEC)	6Digit type: 0.001s-999.999s, 4Digit type: 0.001s-9.999s
	Up/Down mode (IJ-♂)	UP (UP)
	Indication mode(Indicator type)(d5P.n)	TOTAL (EDERL)
	Memory protection(Indicator type) (dRER)	CLEAR (5Lr)
	Output mode (oUL.n)	OND (and)
Timer	OUT2 output time (₀𝒴とჇ)	Hold (Hold)
1	OUT1 output time (oUE 1)	100ms (00. 10)
	Input logic (5/ 6)	NPN (nPn)
	Input signal time (! āŁ)	20ms (20)
	Lock key (LoCY)	Lock off (L.oFF)
	Preset value 1 (PS1)	1000 (000)
	Preset value 2 (PS2)	5000 (5000)
	Communication address (Rddr)	01 (00))
atio	Communication speed (6P5)	9600bps (96)
nic	Communication parity (Prty)	NONE (nonE)
Communication	Communication stop bit (5EP)	2 (2)
Com	Response waiting time (r 5 4)	20ms (20)
	Communication writing ([ចក.ម)	Enable (EnR)

Error display

Error display	Errors	Output status	How to return
PS10 PS20 FAIL	Failed in data loading for exsiting setting values	OFF	Power on again

Factory default



×1. If no key is touched for 60 sec., the counter will return to RUN mode without being restored.

○ Change of preset(Counter/Timer)

• Even if changing the preset value, input operation and output control will continue. In addition, the preset value could be set to 0 and 0 preset value turns ON. According to output mode, preset value could not be set to 0. (When setting to 0, preset value "0" will flash 3 times.)

Function



In Run mode, it enters into the preset value setting mode using 🔇 key. 'PS1' LED lights and first digit of preset value flashes



The preset value is set to '180' using (\mathbf{C}, \mathbf{C}) and (\mathbf{C}, \mathbf{C}) then press (\mathbf{C}, \mathbf{C}) key to enter into the PS2 setting mode.



3sec.: Enters into parameter 1 group

setting mode 5sec.: Enters into parameter 2 group

The preset value is set to '200' using **(**, **(**) and **(**) keys, then press **(**) key to complete PS2 setting and return to Run mode.

* Press key to save set value after changing the setting value. Then, it moves to next parameter or returns to RUN mode. However, if no key is touched for 60 sec., it will return to RUN mode without being saved.

O Function setting check mode

• Setting value of function setting mode can be confirmed using the 🔊 and 🛛 keys.

Switching display function in preset indicator

• Setting value 1(PS1) and setting value 2(PS2) are displayed each time pressing model. (In timer, it is available for and, and I, and 2 output mode.)

O Reset

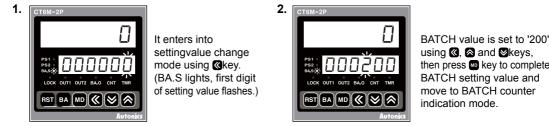
• In Run mode or function setting mode, if key or applying the signal to the RESET terminal on the back side, present value will be initialized and output will maintain off status. When selecting voltage input(PNP), short no. 10 and no. 12 terminals, or when selecting no-voltage input(NPN), short no. 11 and no. 12 terminals to reset.

BATCH Counter(For CT6M-1P //CT6M-2P // model only)

In BATCH counter indication mode, 'BATCH counter value' is displayed in count indicator and 'BATCH counter setting value' is displayed in preset indicator.

O Change of BATCH setting value

If pressing Key in Run mode, it will enter into BATCH counter indication mode.



using (\otimes, \otimes) and (\otimes) keys, then press we key to complete BATCH setting value and move to BATCH counter

Autonics

(A) Photo electric

sensor

(B) Fiber optic sensor

(C) Door/Area

(D) Proximity

(E) Pressure

(F) Rotary encoder

(G) Connector/ Socket

(H) Temp. controller

(I) SSR/ Power controlle

(J) Counter

(K) Timer

(L) Panel

mete

meter

(N) Display unit

(O) Sensor controller

(P) Switching

mode powe supply

(Q) Stepper

motor& Driver&Co

(R) Graphic/ Logic panel

(S) Field network device

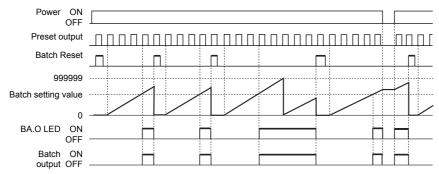
(T) Software

(U) Other

(M) Tacho/ Speed/ Pulse

senso

○ BATCH counter operation



○ BATCH counting operation

• BATCH counting value is increasing until BATCH reset signal applied. BATCH counting value will be circulated when it is over 999999.

1) BATCH counting operation in Counter : Counts the number of reaching setting value of CT6M-1P or reaching dual setting value of CT6M-2P

2) BATCH counting operation in Timer: Counts the number of reaching setting time.

(In case of "FLK" output mode, count the number of reaching T.off setting time and T.on setting time.)

◎ BATCH output

- If input signal is applied while changing BATCH setting value, counting operation and output control will be performed.
- If BATCH count value equals to BATCH setting value, BATCH output will be ON and maintain ON status until BATCH reset signal is applied.
- When the power is cut off then resupplied in status of BATCH output is ON, BATCH output maintains ON status until BATCH reset signal is applied.

○ BATCH reset input

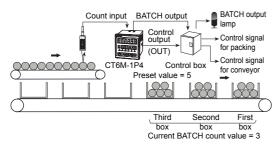
- If pressing reset button or applying the signal to BATCH reset terminal on the back side panel, BATCH counting value will be reset. When selecting voltage input(PNP), short no. 10 and no. 14 terminals, or when selecting no-voltage input(NPN), short no. 11 and no. 14 terminals to reset.
- When BATCH reset is applied, BATCH counting value maintains at 0 and BATCH output maintains in the OFF status.

◎ Application of BATCH counter function

Counter

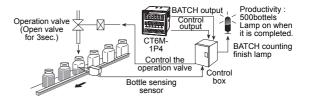
In case, put 5 products in a box then pack the boxes when they reaches to 200.

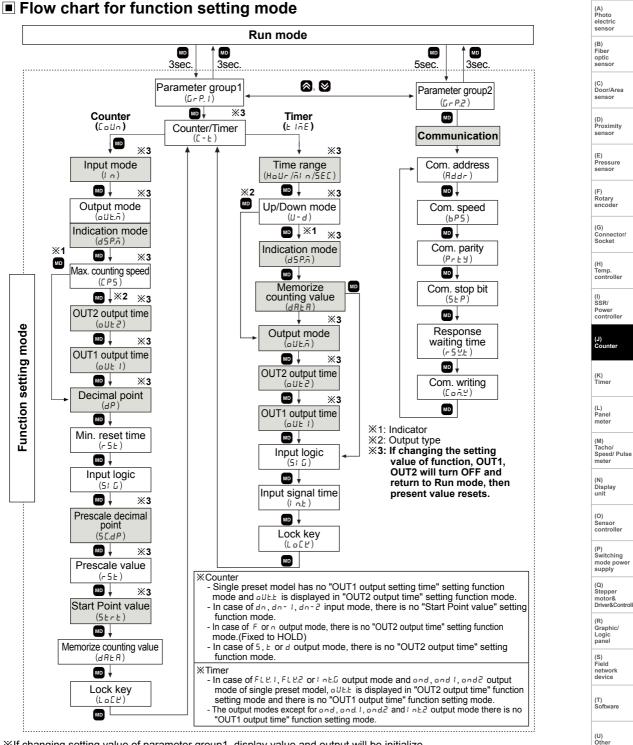
- Counter preset setting value="5", BATCH setting value="200"
- When the count value of counter reaches to the preset value "5", the control output(OUT) will be on, and at this time the count value of the BATCH counter will be increased by "1". The control box which is received the control output (OUT) repeatedly controls conveyor to move the full box and to place the next empty box for standby. When the BATCH count value reaches to "200", BATCH output will be ON. Then the control box stops conveyor and provides a control signal for packing.



• Timer

Fills milk into the bottle for 3sec.(setting time) When 500 bottles are filled, BATCH counting finish lamp is turned on. (Setting time : 3sec., BATCH setting value : 500)





%If changing setting value of parameter group1, display value and output will be initialize.

- ※Press mo key over 3sec./5sec. in RUN mode to enter into parameter 1 group/ parameter 2 group.
- Press we key over 3 sec. in function setting mode to return RUN mode.
- XInput operation and output control can be set in function setting mode.

XIf changing set value of X3 marked parameters in function setting mode, OUT1 and OUT2 output will be turned OFF and then the current value is reset.

%Parameter 2 group is not available to non-communication models.

Parameter setting(Counter)

(wo key: To select setting mode, So or key: To change setting value)

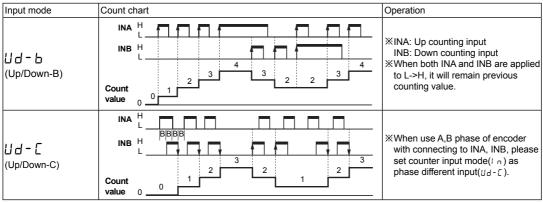
Setting mode	How to set	
Counter/Timer E - E	EaUn ←→ tiñE	೫۲۵∩E: COUNTER ۲ הE: TIMER
Input mode	Ud-C ←→ UP ←→ UP- I ←→ UP-2 ←→ di	n ←> dn- l ←> dn- 2 ←> Ud- A ←> Ud- b
Output mode อปะ.กิ Indication mode d5P.กิ	Ud-R, Ud-b, Ud-C input mode F ← P ← P ← C ← P ← P ← P ← P ← P ← P ← P	→ R → is no "OUT2 output time" setting mode. (Fixed to HOLD) ※If output mode is set to d when max. counting
Max. counting speed	30 ← > 12 ← > 59 ← > 102 ← > 1 and it is	g speed is that of one by one(1:1) duty ratio of INA or INB input signal, applied in INA and INB at thesame time. of setting a in output mode, you can choose 1cps, 30cps, 1Kcps.
OUT2 output time 미노근	 G : To shift flashing digit position of OUT2 output time value. ⊠ A : To change OUT2 output time value 	XSetting range: 0.01 to 99.99 sec.
OUT1 output time	 G : To shift flashing digit position of OUT1 output time value. ⊠	%Time range: 0.01 to 99.99 sec., Hold
≭ 1 Decimal point dP	6digit type 4digit type 4digit type	 Setting the decimal point is applied same to counting value and setting value.
Min. reset time - 5£	/ ← → 20 unit: ms	XSet the min. external RESET signal width.
Input logic 5៖ ធ	nPn: No-Voltage input PnP: Voltage input	XCheck input logic value(PNP, NPN).
* 1 Prescale decimal point 5 <i>C.dP</i>	Gdigit type Adigit type Adigit type	 Prescale decimal point position is not set below the decimal point setting digits (dP).
Prescale value	 I to shift the flashing digit. I to change the prescale value. 	 Setting range of prescale value 6digit type: 0.00001 to 99999.9 4digit type: 0.001 to 999.9 Setfer to the J-20 page [Prescale function'.
Start Point Value	 It is shift the flashing digit. It is change the Start Point value. 	 Setting range of Start Point value (Connected with decimal point setting) 6digit type: 0.0000 to 999999 4digit type: 0.000 to 9999 Refer to the J-20 page I Start Point function'.
Memory protection		itializes count value when power is off. lemorizes count value at the moment of power off.
Lock key LoCE	$LoFF \longleftrightarrow LoC.1 \qquad \qquad$	Ø, ⊗ keys.

%1. Explanation of decimal point and prescale decimal point setting

- Decimal point setting : Set decimal point of the display value on front indicator.
 - Prescale decimal point setting : Set prescale decimal point of counting regardless of decimal point of display value on front indicator.

Input mode	Count chart	Operation	sensor
			(B) Fiber optic sensor
(UP)	INB L No counting 5 6	 If INA is counting input, INB is inhibition input. If INB is counting input, INA is 	(C) Door/Area sensor
	Count 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	inhibition input.	(D) Proximity sensor
			(E) Pressure sensor
∐ ₽- (Up-1)	INB L No counting 4	(_▲) ×INA: Counting input	(F) Rotary encoder
	Count 2 3 value 1 0 0		(G) Connector/ Socket
		XCounts when INA input signal is	(H) Temp. controller
∐ ₽ - 2 (Up-2)	INB H No counting 2	down. () XINA: Counting input	(I) SSR/ Power controller
	Count 1 value 0		(J) Counter
1		i ≫ If INA is counting input, INB is	(K) Timer
Down) INB H n n-1 n-2 n-3	(L) Panel meter		
	Count <u>1 -4 n-5 n-6 n-7</u>		(M) Tacho/ Speed/ Pulse meter
			(N) Display unit
dn - 1 (Down-1)	$\begin{array}{c c} & & & & & \\ \hline & & & & & \\ \hline & & & & & \\ \hline & & & &$	(_►) ×INA: Counting input	(O) Sensor controller
	Count n-4 n-5		(P) Switching mode power supply
			(Q) Stepper motor& Driver&Controlle
d n - 2 (Down-2)	n $n-1$ $n-2$ $n-3$	XINA: Counting input	(R) Graphic/ Logic panel
	Count <u>value</u> 0 <u> </u>		(S) Field network device
U - A		XINA: Counting input INB: Counting command input	(T) Software
(Up/Down-A)	Count value $_{0}$ $_{1}$ $_{2}$ $_{3}$ $_{4}$ $_{3}$ $_{2}$ $_{1}$ $_{2}$ $_{3}$ $_{4}$ $_{3}$ $_{2}$ $_{1}$ $_{2}$ $_{1}$ $_{2}$ $_{3}$ $_{4}$ $_{3}$ $_{2}$ $_{1}$ $_{2}$ $_{3}$ $_{4}$ $_{3}$ $_{2}$ $_{1}$ $_{2}$ $_{3}$ $_{4}$ $_{3}$ $_{2}$ $_{1}$ $_{2}$ $_{3}$ $_{3}$ $_{4}$ $_{3}$ $_{2}$ $_{1}$ $_{2}$ $_{3}$ $_{3}$ $_{4}$ $_{3}$ $_{2}$ $_{1}$ $_{2}$ $_{3}$ $_{3}$ $_{4}$ $_{3}$ $_{2}$ $_{1}$ $_{2}$ $_{3}$ $_{3}$ $_{4}$ $_{3}$ $_{2}$ $_{1}$ $_{2}$ $_{3}$ $_{3}$ $_{4}$ $_{3}$ $_{2}$ $_{3}$ $_{3}$ $_{3}$ $_{4}$ $_{3}$ $_{2}$ $_{3}$ $_{3}$ $_{3}$ $_{3}$ $_{4}$ $_{3}$ $_{2}$ $_{3}$ $_{$	When INB is L, counting Up. When INB is H, counting Down.	(U) Other

Input operation mode(Counter)

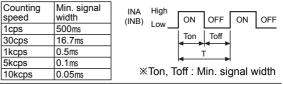


※@ signal width should be over min. signal width and b signal width should be over a half min. signal width. If not, ±1 will occur.

*The meaning of "H" and "L"

	Voltage input (NPN)	No-Voltage input (PNP)		
н	5-30VDC	Short circuit		
L	0-2VDC	Open		

*Min. signal width by counting speed

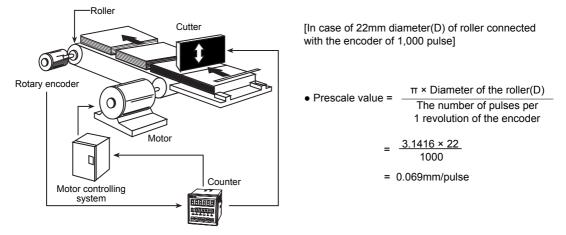


Prescale function(Counter)

This function is to set and indicate calculated unit for actual length, liquid measure, position etc. It is called "Prescale value" for measured length, measured liquid, measured position, etc per 1 pulse.

For example, P is the number of pulses per 1 revolution of a rotary encoder and L is the desired length to be measured. Prescale value is [the desired length (L)]/[the number of pulses (P) per 1 revolution of the rotary encoder.]. It is the length per 1 pulse of a rotary encoder.

Ex) Control length by the counter and the rotary encoder



To control conveyor position in 0.1mm, set the decimal point to tenth place(-----) in decimal point setting mode(\mathcal{AP}) and set the prescale decimal point to thousandth place(----) in prescale decimal point setting mode(\mathcal{SLAP})Then set prescale value "0.069" in prescale setting mode (\mathcal{SL}).

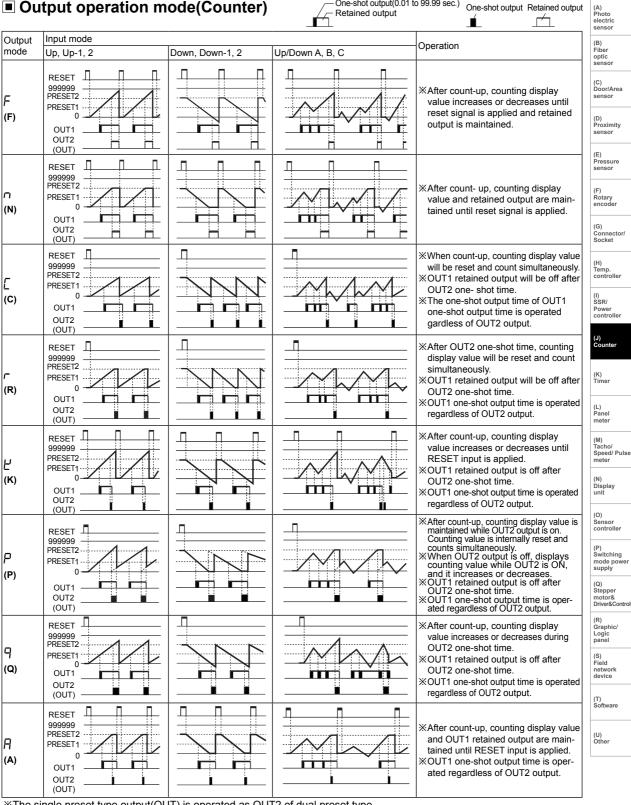
Start point function(Counter)

This function is that start point value works as initial value when on counting mode.

- In case of dn, dn- 1 or dn-2 in timer input mode, it is not available.
- When reset is applied, the present value is initialized to start point.
- After count up in [, r, P, 9 After count up in

Output operation mode(Counter)

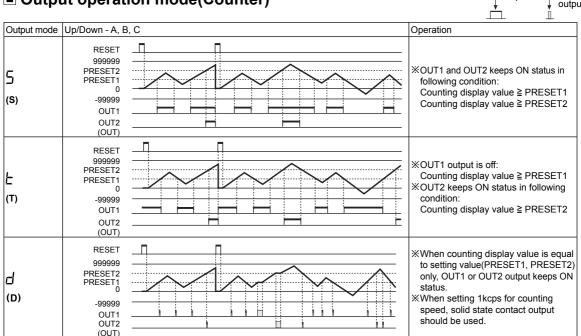
One-shot output(0.01 to 99.99 sec.) One-shot output Retained output Retained output ŕ Í



*The single preset type output(OUT) is operated as OUT2 of dual preset type. *OUT1 output could be set to 0 in all modes and 0 value output turns ON. ※OUT2 output could not set to 0 in C(E). R(r), P(P) or Q(P) output mode.

Output operation mode(Counter)

Retained output Coincidence



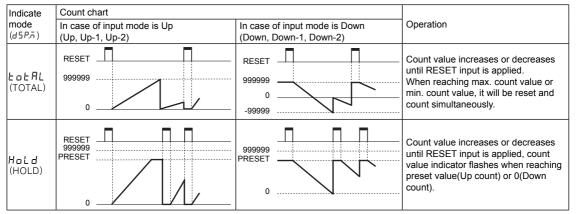
%The single preset type output(OUT) is operated as OUT2 of dual preset type.

The dual preset model OUT1 output is operated as one-shot or retained output.(except 5, Ł, d mode)

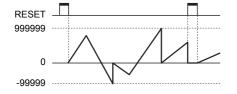
XOUT1 output could be set to 0 in all modes and 0 value output turns ON.

OUT2 output could not set to 0 in C([), R(r), P(P) or Q(9) output mode.

Counter operation of the indicator(CT6S-I, CT6Y-I, CT6M-I)



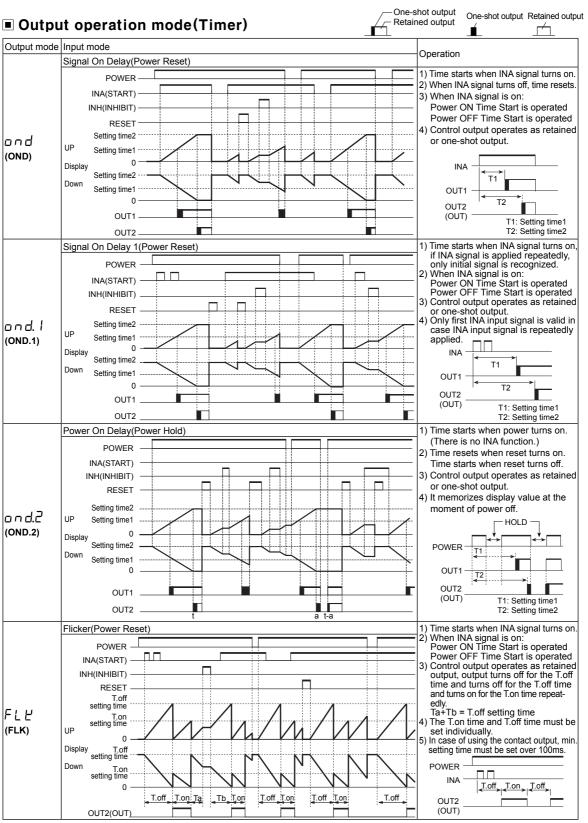
• In case of the input mode is Command input (Ud-R), Individual input(Ud-b), Phase difference input(Ud-C).



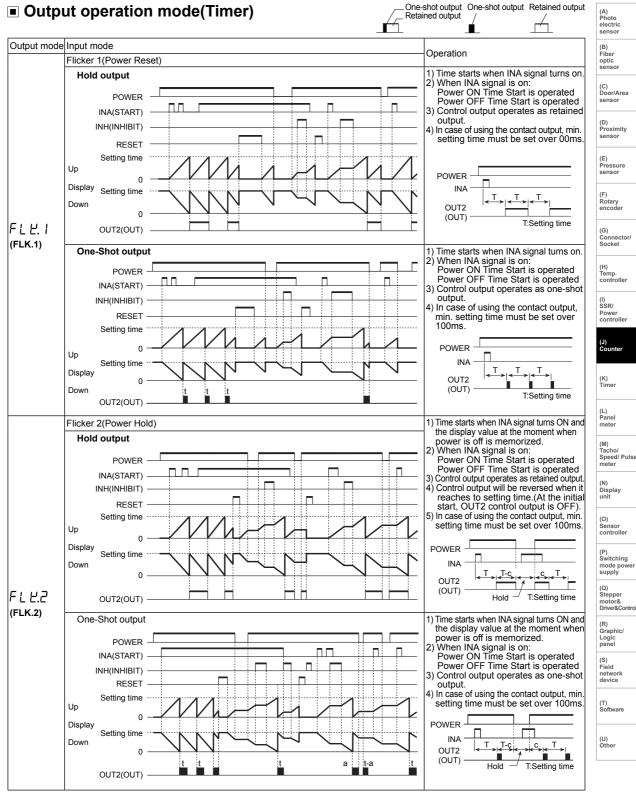
*In case of UP/DOWN (Ud-A, Ud-b, Ud-L) input mode, indication mode (d5P.5) of the configuration is not displayed. Parameter setting(Timer)

(₩ key: To select setting mode ♥ or ♠ key: To change setting value)

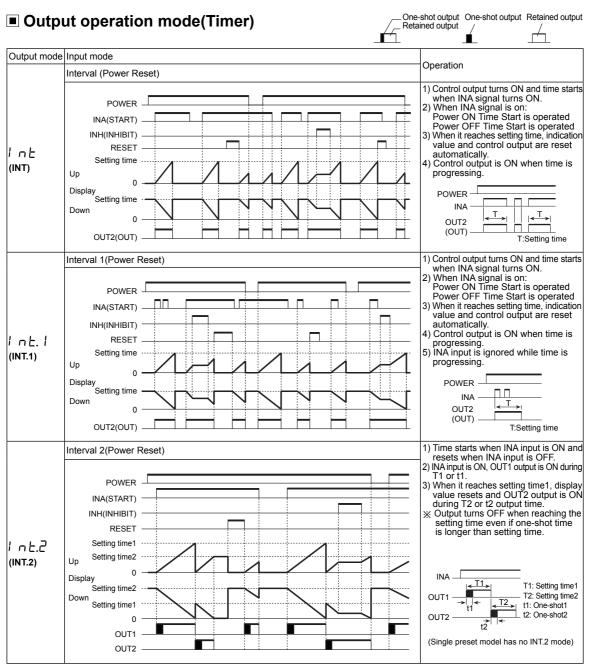
	(key: 10 select setting mode of a key: 10 change setting valu	sensor
Setting mode	How to set	(B) Fiber
Counter/Timer	Colln ←→ El ñE ×Colln: COUNTER El ñE: TIMER	optic sensor
	• 6digit type	(C) Door/Area sensor
	5EC 5EC <td>(D) Proximity sensor</td>	(D) Proximity sensor
	999.999s 9999.99s 99999.9s 999999s 99m59.9s Hour Hā Hā Sāin āin āin ā S	(E) Pressure sensor
Timer range Hollr /ลียด/SEC	Image: Second state	(F) Rotary encoder
	• Adigit type SEC SEC SEC SEC	(G) Connector/ Socket
	9.999 99.99 999.98 999.98 999.98	(H) Temp. controller
		(I) SSR/ Power controller
	$H_{\underline{0}}U_{\underline{1}} \leftrightarrow H_{\underline{0}}\overline{1} \leftrightarrow \underline{\overline{1}}\overline{1}$ $(H_{\underline{0}}U_{\underline{1}}) \leftrightarrow H_{\underline{0}}\overline{1}\overline{1} \leftrightarrow \underline{\overline{1}}\overline{1}\overline{1}$ $(H_{\underline{0}}U_{\underline{1}}) \leftrightarrow H_{\underline{0}}\overline{1}\overline{1} \to \underline{\overline{1}}\overline{1} \to \underline{\overline{1}}\overline{1}\overline{1}$ $(H_{\underline{0}}U_{\underline{1}}) \leftrightarrow H_{\underline{0}}\overline{1}\overline{1} \to \underline{\overline{1}}\overline{1} \to \underline{\overline{1}}\overline{1}\overline{1}$ $(H_{\underline{0}}U_{\underline{1}}) \leftrightarrow H_{\underline{0}}\overline{1} \to \underline{\overline{1}}\overline{1} \to \underline{\overline{1}}\overline{1}$ $(H_{\underline{0}}U_{\underline{1}}) \leftrightarrow H_{\underline{0}}\overline{1} \to \underline{\overline{1}}\overline{1} \to \underline{\overline{1}}\overline{1} \to \underline{\overline{1}}\overline{1}$ $(H_{\underline{0}}U_{\underline{1}}) \leftrightarrow H_{\underline{0}}\overline{1} \to \underline{\overline{1}}\overline{1} \to \underline{\overline{1}} \to \underline{\overline{1}}\overline{1} \to \underline{\overline{1}} \to \underline{\overline{1}}\overline{1} \to \underline{\overline{1}}\overline{1} \to \underline{\overline{1}}\overline{1} \to \underline{\overline{1}} \to \underline{\overline{1}} \to \underline{\overline{1}}\overline{1} \to \underline{\overline{1}} \to \underline{\overline{1}} \to \underline{\overline{1}}\overline{1} \to \underline{\overline{1}} \to $	(J) Counter
UP/DOWN mode	UP ← → dn XUP: Time proceeds from 0 to the setting value. Xdn: Time proceeds from the setting value to 0.	(K) Timer
Indication mode	LotRL → Hold → onLd *Used for the indicator only. * It is added that the feature which set the setting time when selecting Hold or onLd (Refer to J-28 page Timer	(L) Panel meter
	operation for the indicator'). XUsed for the indicator only.	(M) Tacho/ Speed/ Pulse meter
Memory protection	$\begin{array}{ccc} & & & & & & \\ \hline & & & & & \\ \hline & & & & &$	(N) Display unit
Output mode שוו ה	$and \leftrightarrow and i \leftrightarrow and 2 \leftrightarrow FLU \leftrightarrow FLU i \leftrightarrow FLU 2 \leftrightarrow int$	(O) Sensor controller
	 	(P) Switching mode power supply
OUT2 output time	Set oUT2 one-shot output time. XSetting range: 0.01 to 99.99sec. XHaLd is displayed by pressing key 4 times.	(Q) Stepper motor& Driver&Controller
OUT1 output time	 It is a shift flashing digit position of OUT1 output time value. It is a shift flashing OUT1 output time value. 	(R) Graphic/ Logic panel
oUE I	 ※Set OUT1 one-shot output time. ※Setting range: 0.01 to 99.99sec., Hold ※HaLd is displayed by pressing	(S) Field network device
Input logic 5 /፲	XnPn: No-Voltage input %Check input logic value(PNP, NPN). XPnP: Voltage input %Check input logic value(PNP, NPN).	(T) Software
Input signal time	<pre>%CTS/CTY: Set min. external INA, INH, RESET signal width. %CTM: Set min. external INA, RESET, INHIBIT, BATCH RESET signal width.</pre>	(U) Other
Lock key LoEE	$L \circ FF \longleftrightarrow L \circ E.1 \qquad \qquad & \times L \circ FF: \text{ Cancellation of the lock mode} \\ \uparrow \qquad \uparrow \qquad \qquad L \circ E.1: Locks $$$$$$$$$$$$$$$$$$$$$$$$$$$$$$$$$$$$$	



%Power Reset: There is no memory protection.(Initializes the display value when power is off) Power Hold: There is memory protection.(Memorizes the display value at the moment of power off, indicates the memorized display value when power is resupplied.)

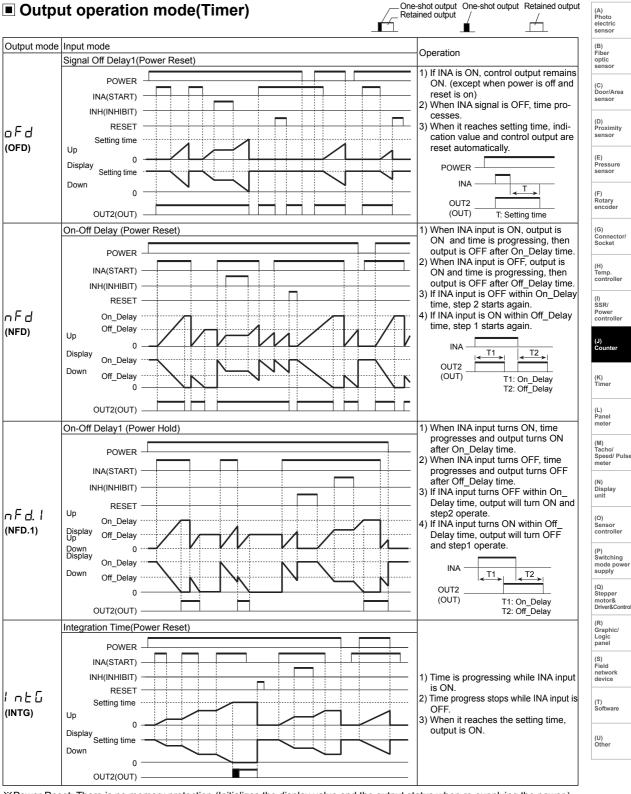


%Power Reset: There is no memory protection.(Initializes the display value when power is off) Power Hold: There is memory protection.(Memorizes the display value at the moment of power off, indicates the memorized display value when power is resupplied.)

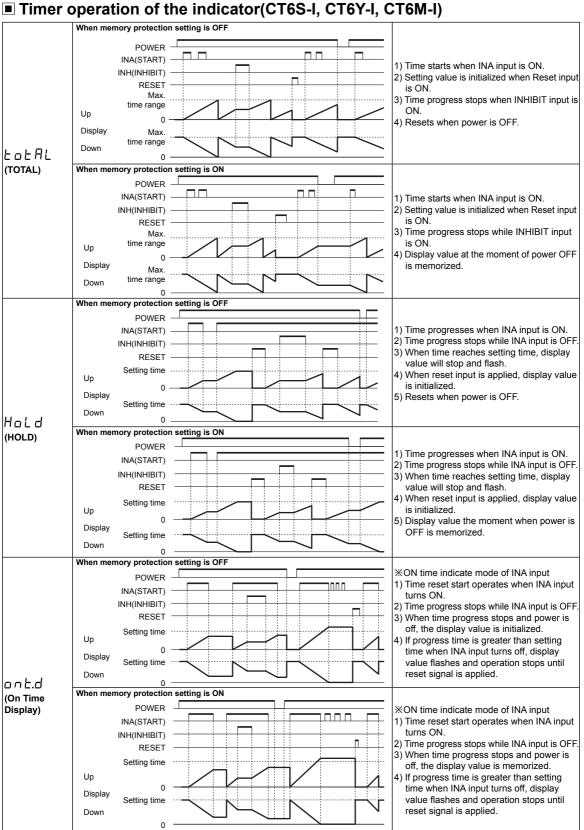


* Power Reset: There is no memory protection. (Initializes the display value when power is off)

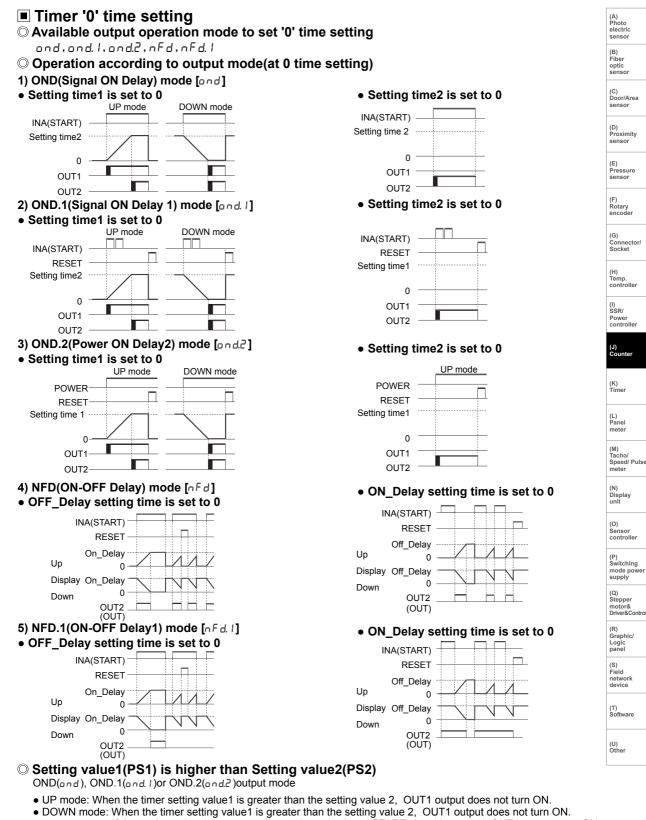
Power Hold: There is memory protection.(Memorizes the display value at the moment of power off, indicates the memorized display value when power is resupplied.)



※Power Reset: There is no memory protection.(Initializes the display value and the output status when re-supplying the power.) Power Hold: There is memory protection.(It memorizes the status of power off. When re-supplying the power, it returns the memorized display value and the output status.)



Programmable Counter/Timer



If the setting value 1 is same as the setting value2 and START signal is applied, OUT1 output turns ON immediately.

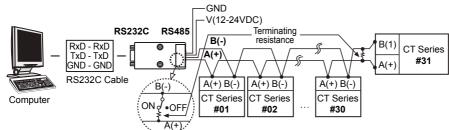
Communication mode

○ Parameter setting

(we key: To select setting mode, So or key: To change setting value)

Setting mode	How to set							
Com. address (Rddr)	 It is shift flashing digits of Com. address. It is same address is applied during multicom., it will not work correctly. 							
Com. speed (ЬР5)	24 ↔ 48 ↔ 95 ↔ 192 ↔ 384 ※2400/4800/9600/19200/38400bps							
Com. parity (Pr ヒリ)	nonE							
Com. stop bit (5 E P)	1 ←→ 2							
	XSetting range according to com. speed.							
	(3): To shift flashing digits position of com. 2400bps [16ms to 99ms]							
esponse waiting time	response waiting time. 4800bps 8ms to 99ms							
(- 5 <u>- 5</u>)	Section 9600bps 5ms to 99ms							
(])	value. 19200bps 5ms to 99ms							
	38400bps 5ms to 99ms							
Com. write (โอกี.ษี)	Enfl							

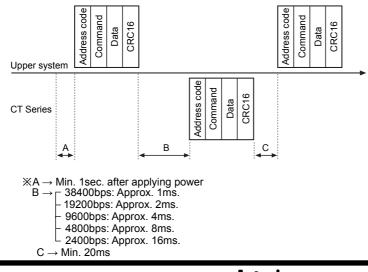
○ Application of system organization



XIt is recommended to use communication converter, RS485 to Serial converter(SCM-38I, sold separately), USB to RS485 converter(SCM-US48I, sold separately). Please use a proper twist pair for RS485 communication.

Communication control ordering

- 1. The communication method is Modbus RTU(PI-MBUS-300-REV.J).
- 2. After 1sec. of power supply into the high order system, it starts to communicate.
- 3. Initial communication will be started by the high order system. When a command comes out from the high order system, CT Series will respond.



Communication command and block

The format of query and response

1) Read Coil Status(Func 01 H), Read Input Status(Func 02 H

Query(Master)

Slave Address							Error Check (CRC 16)	
		High	Low	High	Low	Low	High	
1Byte	1Byte	1Byte	1Byte	1Byte	1Byte	1Byte	1Byte	
4					~			

CRC 16

Response(Slave)

Slave Address	Function	Byte Count	Data	Data		Error Check (CRC 16) Low High	
1Byte	1Byte	1Byte	1Byte	1Byte	1Byte	1Byte	1Byte

CRC 16

2) Read Holding Registers(Func 03 H), Read Input Registers(Func 04 H)

Query(Master)

Slave Address	Function	Starting Address		No. of F	oints	Error Check (CRC 16)		
Audress		High	Low	High	Low	Low	High	
1Byte	1Byte	1Byte	1Byte	1Byte	1Byte	1Byte	1Byte	

CRC 16

Response(Slave)

SI	Slave Address	Function	unction Byte Count	Data		Data		Data		Error Check (CRC 16)		
A				High	Low	High	Low	High	Low	Low	High	
16	Byte	1Byte	1Byte	1Byte	1Byte	1Byte	1Byte	1Byte	1Byte	1Byte	1Byte	

CRC 16

3) Force Single Coil(Func 05 H)

Query(Master)

Slave		Coil Add	dress	Force D		Error Check (CRC 16)		
Address		High	Low	High	Low	Low	High	
1Byte	1Byte	1Byte	1Byte	1Byte	1Byte	1Byte	1Byte	

CRC 16

Response(Slave)

High Low High Low Low High	Slave Address	Function	Coil Add	lress	Force D	ata	Error Check (CRC 16)		
4 Di ta	Address		High	Low	High	Low	Low	High	
TByte TByte TByte TByte TByte TByte TByte	1Byte	1Byte	1Byte	1Byte	1Byte	1Byte	1Byte	1Byte	

CRC 16

4) Preset Single Register(Func 06 H) Query(Master)

Address High Low High Low Low High 1Byte 1Byte	Slave Address	Function	Register Address		Preset [Data	Error Check (CRC 16)		
1Byte 1Byte 1Byte 1Byte 1Byte 1Byte 1Byte			High	Low	High	Low	Low	High	
	1Byte	1Byte	1Byte	1Byte	1Byte	1Byte	1Byte	1Byte	

CRC 16

• Res	Response(Slave)											
Slave	Function	Register Address		Preset [Data	Error Check (CRC 16)						
Address		High	Low	High	Low	Low	High					
1Byte	1Byte	1Byte	1Byte	1Byte	1Byte	1Byte	1Byte					

CRC 16

5) Preset Multiple Registers(Func 10 H)

Query(Master)

,	5) Preset Multiple Registers(Func 10 H) Query(Master)									(B) Fiber optic sensor				
Slave Address	Function	Starti Addre		No. o Regis		Byte Count	Data		Data			Error Check (CRC 16)		(C) Door/Area sensor
		High	Low	High	Low		High	Low	High	Low	Low	High		(D)
1Byte	1Byte	1Byte	1Byte	1Byte	1Byte	1Byte	1Byte	1Byte	1Byte	1Byte	1Byte	1Byte	Proximi sensor	

CRC 16

Response(Slave)

Slave	Function	Starting A	Address	No. of Re	nister	Error Check (CRC 16)		
Address		High	Low	High	Low	Low	High	
1Byte	1Byte	1Byte	1Byte	1Byte	1Byte	1Byte	1Byte	
-	·	•	•		•			

CRC 16

6) Application

Read Coil Status(Func 01 H) Master reads OUT2 00002(0001H) to 00003(0002H), OUT1 output status(ON : 1, OFF : 0) from the Slave(Address 01).

Query(Master)

Slave	Function			No. of Po	ints	Error Check (CRC 16)		
Address		High	Low	High	Low	Low	High	
01 H	01 H	00 H	01 H	00 H	02 H	EC H	0B H	

On slave side OUT2 00003(0002H) : OFF, OUT1 00002(0001H) : ON

Response(Slave)

Slave Address	Function	Byte Count	(00003 to	Error Check (CRC 16)		(M) Tach
Address			00001)	Low	High	Spee
01 H	01 H	01 H	02 H	D0 H	49 H	

Read Input Register (Func 04 H)Master reads preset value 21004(03EBH) to 21005(03ECH) of counter/timer, Slave (Address 15).

Query(Master)

Slave									
Address	. anotion	High	Low	High	Low	Low	High		mode po supply
0F H	04 H	03 H	EB H	00 H	02 H	00 H	95 H		(Q)
In area that the present value is 122456(0001 5240 LI) in									

In case that the present value is 123456(0001 E240 H) in slave side, 31004(03EBH): E240 H, 31005(03ECH): 0001H

Response(Slave)

Slave			Data		Data		Error Ch (CRC 16		
Address			High	Low	High	Low	Low	High	
0F H	04 H	04 H	E2 H	40 H	00 H	01 H	E2 H	28 H	

imity or (E) Pressure (F) Rotary encoder (G) Connector/ Socket

(A) Photo electric sensor

(H) Temp. controller

(I) SSR/ Power controller

(J) Cou

(K) Timer

(L) Panel meter

10/ ed/ Pulse

(N) Display unit

(O) Sensor controller

motor& Driver&Co (R) Graphic/ Logic panel

(S) Field network device

(T) Software

(U) Other

○ Modbus Mapping Table

1) Reset/Output

No(Address)	Func	Explanation	Setting range	Notice
00001(0000)	01/05	Reset	0:OFF 1:ON	
00002(0001)	01	OUT2 output	0:OFF 1:ON	
00003(0002)	01	OUT1 output	0:OFF 1:ON	
00004(0003)	01	BATCH output	0:OFF 1:ON	For BATCH output model
00005(0004)	01/05	BATCH resets	0:OFF 1:ON	For BATCH output model

2) Terminal input status

		1		
No(Address)	Func	Explanation	Setting range	Notice
10001(0000)	02	INA input status	0:OFF 1:ON	Terminal input
10001(0000)	02	INA Input status	U.OFF I.ON	status
10002(0001)	02	INB input status	0:OFF 1:ON	Terminal input
10002(0001)	02		U.OFF I.ON	status
10002(0002)			0:OFF 1:ON	Terminal input
10003(0002)	02	INHIBIT input status	U.OFF I.ON	status
10004(0003)	02		0:OFF 1:ON	Terminal input
10004(0003)	004(0003) 02 RESET input status		U.OFF I.ON	status
10005(0004)	02	BATCH RESET	0:OFF 1:ON	Terminal input
10003(0004)	02	input status	0.011 1.014	status

3) Product Information

Func	Explanation	Notice	
04	Reserved	—	
04	Product number H	Madel ID	
04	Product number L	Model ID	
04	Hardware version		
04	Software version	—	
04	Model no. 1	"CT"	
04	Model no. 2	"6M"	
04	Model no. 3	"-2"	
04	Model no. 4	"PT"	
04	Reserved		
04	Reserved	—	
04	Reserved		
04	Reserved	 	
04	Reserved		
04	Reserved	—	
04	Coil Status Start Address	0000	
04	Coil Status Quantity	—	
04	Input Status Start Address	0000	
04	Input Status Quantity	—	
04	Holding Register Start Address	0000	
04	Holding Register Quantity	<u> </u>	
04	Input Register Start Address	0064	
04	Input Register Quantity	_	
	04 04	04 Reserved 04 Product number H 04 Product number L 04 Hardware version 04 Software version 04 Model no. 1 04 Model no. 2 04 Model no. 3 04 Model no. 4 04 Reserved 04 Coil Status 04 Coil Status 04 Coil Status 04 Input Status Quantity 04 Input Status Quantity 04 Holding Register Start Address 04 04 Holding Register Quantity	

4) Monitoring data

No(Address)	Func	Explanation	Setting range	Notice	
		BA.O LED display status	0:OFF 1:ON	Bit 5	
		OUT2 LED display status	0:OFF 1:ON	Bit 6	
		OUT1 LED display status	0:OFF 1:ON	Bit 7	
		BA.S LED display status	0:OFF 1:ON	Bit 10	
31001 (03E8)	04	LOCK LED display status	0:OFF 1:ON	Bit 11	
		PS2 LED display status	0:OFF 1:ON	Bit 12	
		PS1 LED display status	0:OFF 1:ON	Bit 13	
		TMR LED display status	0:OFF 1:ON	Bit 14	
		CNT LED display status	0:OFF 1:ON	Bit 15	
31002(03E9)	04	Present value of BATCH	0 to 999999	For BATCH output	
31003(03EA)	04	counter	0.0000000	model	
31004(03EB)			Counter 6digit type: -99999 to		
31005(03EC)	04	Present value of counter/timer	4digit type: -99999 to 999999 4digit type: -999 to 9999 Timer: Within time setting range	Use counter and timer in common	
31006(03ED)	04	Display unit	Counter: decimal point of display value Timer: Time range	Counter: 40058 Data Timer: 40102 Data	
31007(03EE)			Counter 6digit type: -99999 to	Use counter	
31008(03EF)	04	PS(2) setting value	4digit type: -999 to 9999 Timer: Within time setting range	and timer in common	
31009(03F0)			Counter 6digit type: -99999 to	Use counter	
31010(03F1)	3F1) 04 PS1 setting value		999999 4digit type: -999 to 9999 Timer: Within time setting range	and timer in common	
31011(03F2)	04	Setting value of BATCH	0 to 999999	Use counter and timer	
31012(03F3)	04	counter		in common	
31013(03F4)	04	Checking the input logic	0: NPN, 1 : PNP		

• Date format of 31001(03E8) address bit

Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit4	Bit 3	Bit 2	Bit 1	Bit 0
CNT	TMR	PS1	PS2	LOCK	BA.S	-	-	OUT1	OUT2	BA.O	-	-	-	-	—
0 or 1	0	0	0 or 1	0 or 1	0 or 1	0	0	0	0	0					

%2 Words data format: Upper data has high number address. Ex)31004 : Present Value(Low Word), 31005 : Present Value(High Word)

5) Preset value setting group

No(Address)			Setting range	Notice
40001(0000)	03	PS2 setting value	Counter 6digit type: 0 to	Use counter and timer
40002(0001)	06 16		000000	in common
40003(0002)	03 06	PS1 setting	4digit type: 0 to 9999 Timer: Within time	Use counter and timer
40004(0002)	16	value	setting range	in common
40005(0004)	00	BATCH coun-	0 to 999999	Use counter and timer
40006(0005)	06 16	ter setting value	0 10 999999	in common

6) Function setting mode (Counter group)

No(Address)	Func	Explanation	Setting range	Notice	Photo electric sensor
40051(0032)	03/06/16	Counter/Timer([- +)	1:CoUn 1:ElñE	Use counter and timer in common	
40052(0033)	03/06/16	Input mode(I n)	0:UP 5:dn-2 1:UP-I 6:Ud-R 2:UP-2 7:Ud-b 3:dn 8:Ud-C 4:dn-I	-	(B) Fiber optic sensor (C) Door/Area sensor
40053(0034)	03/06/16	Indication mode(d) 55)	O: Lot AL 1: Hold	For the indicator	
40054(0035)	03/06/16	Output mode(ם U ב הَ)	0:F 3:r 6:9 9:E 1:n 4:E 7:R 10:d 2:C 5:P 8:5	—	(D) Proximity sensor
40055(0036)	03/06/16	Maximum counting speed([P5)	0: 1 2: 12 4: 102 1: 30 3: 52	—	(E) Pressure sensor
40056(0037)	03/06/16	OUT2(OUT) output time	000 1~9999	unit: ×10ms	
40057(0038)	03/06/16	OUT1 Output time	000 1~9999	unit: ×10ms	(F)
40058(0039)	03/06/16	Decimal point(dP)	0: 2: 4: 1: 3: 5:	4digit type 0: 1: 2: 3:	Rotary encoder
40059(003A)	03/06/16	Min. reset time(r 5 L)	0: / 1:20	unit: ms	(G)
40060(003B)	03/06/16	Prescale decimal point position (5 [L.d)	0: 3: 5:	4digit type 1: 2: 3:	Connecto Socket
40061(003C) 40062(003D)	03/06/16	Prescale value(5[L)	6digit type: 0.0000 / to 999999 4digit type: 0.00 / to 9999	Connected with prescale decimal point position	(H) Temp. controller
40063(003E) 40064(003F)	03/06/16	Start value(5 Ł r Ł)	6digit type: 000000 to 999999 4digit type: 0000 to 9999	Connected with decimal point position of display value	(I) SSR/
40065(0040)	03/06/16	Memory protection (d R L R)	0: ELr 1: r E E	Use counter and timer	Power
40066(0041)	03/06/16	Lock key(LoEY)	0:L.oFF 1:LoC. / 2:LoC.2 3:LoC.3	in common	controller

7) Function setting mode (Timer group)

.,		mode (inner group	,		
No(Address)	Func	Explanation	Setting range	Notice	
40101(0064)	03/06/16	Counter/Timer([-+)	0:EoUn 1:ElñE	Use counter and timer in common	(K) Timer
			4digit type		
			0: 0.001s to 9.999s 5: 0.1m to 999.9m 1: 0.01s to 99.99s 6: 1m to 9999m		(L) Panel meter
		Time renge	2: 0.1s to 999.9s 7: 1m to 99h59m 3: 1s to 9999s 8: 1h to 9999h 4: 1s to 99m59s 8: 1h to 99m59h		(M) Tacho/ Speed/ Pulse meter
40102(0065)	03/06/16	Time range (Hour /āi o /5EE)	6digit type	1—	(41)
			0: 0.001s to 999.999s 6: 1s to 9999m59s 1: 0.01s to 9999.99s 7: 1m to 99999.9m		(N) Display unit
		2: 0.1s to 99999.9s 8: 1m to 999999m 3: 1s to 999999s 9: 1s to 99h59m59s 4: 0.01s to 99m59.99s 10: 1m to 9999h59m 5: 0.1s to 999m59.9s 11: 0.1h to 99999.9h		(O) Sensor controller	
40103(0066)	03/06/16	UP/Down mode (U - d)	0: UP 1: dn		(P) Switching mode power supply
40104(0067)	03/06/16	Output mode (อยะลั)	0: ond 3:FLY 7:Int.I 10:nFd 1: ond I 4:FLY.I 8:Int.2 11:nFd I 2: ond 2 5:FLY.2 9:oFd 12:Int.6	-	(Q) Stepper motor& Driver&Controller
40105(0068)	03/06/16	OUT2(OUT) Output time (₀ ⊔ է ₴)	0000 to 9999(0: Hold)	unit: ×10ms	(R) Graphic/ Logic
40106(0069)	03/06/16	OUT1 Output time	0000 to 9999(0:Hold)	unit: ×10,ms	panel (S)
40107(006A)	03/06/16	Input signal time(I n E)	0: / 1:20	unit: ms	Field
40108(006B)	03/06/16	Memory protection (dRER)	0: ELr 1: rEE	Use counter and timer in common	device
40109(006C)	03/06/16	Lock key(Lo[U)	0:L.oFF 1:Lo[. 2:Lo[.2 3:Lo[.3	Use counter and timer in common	(T)
40110(006D)	03/06/16	ndication mode(d 5 P.n.)	0: LotAL 1: Hold 2: ont.d	For the indicator	(T) Software

(U) Other

(J) Counter

8) Function setting mode (Communication group)

No(Address)	Func	Explanation	Setting range	Notice
40151(0096)	03/06/16	Com. address (月ddr)	1 to 127	—
40152(0097)	03/06/16	Com. speed (6 P 5)	0:24 1:48 2:96 3:192 4:384	unit: ×100bps
40153(0098)	03/06/16	Com. parity (P - 눈 님)	0:nonE 1:EuEn 2:odd	_
40154(0099)	03/06/16	Stop bit (5 Ł P)	0: / 1: 2	
40155(009A)	03/06/16	Response waiting time (r 5 4. L)	05 to 99	unit: ms
40156(009B)	03/06/16	Com. writing ([= ā.])	0:EnA 1:d/5A	

○ Exception processing

When communication error occurs, the highest bit of received function is set to 1, then sends response command and transmits exception code.

Slave Address	Function+80H	Exception Code	Error Check(CRC16)		
			Low	High	
1Byte	1Byte	1Byte	1Byte	1Byte	

Illeegal Function(Exception Code: 01H): Not supporting command

• Illegal Data Address(Exception Code: 02H): Mismatch between the number of asked data and the number of transmittable data.

- Illegal Data Value(Exception Code: 03H): Mismatch between asked the number of data and transmittable the number of data in device
- Slave Device Failure(Exception Code: 04H): Command is processed incorrectly.

Example)

Master reads output status (ON:1, OFF:0) of non existing coil 01001 (03E8 H) from Slave (Address17).

• Query(Master)

Slave Address Function	Function	Starting Address N		No. of Points		Error Check(CRC16)	
	Function	High	Low	High	Low	Low	High
11H	01H	03H	E8H	00H	01H	##H	##H

Response(Slave)

Slave Address	Function + 80H	Exception Code	Error Check(CRC16)		
			Low	High	
11H	81H	02H	##H	##H	

Read and write of parameter value using communication

Read of the parameter area

00002(OUT2), 00003(OUT1), 00004(BA, 0), 10001 to 10005(Terminal input), 30101 to 30125(Product information), 31001 to 31013(Monitoring data)

Read and write of the parameter area

00001(Reset starts), 00005(BATCH Reset starts), 40001 to 40006(Setting value saving group), 40051 to 40066(Counter setting group), 40101 to 40110(Timer setting group), 40151 to 40156(Communication setting group)

Read of communication

Read parameter value using communication.(Function : 01H, 02H, 03H, 04H)

It is able to read communication regardless of permitting/prohibiting communication writing.

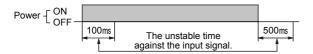
Communication write

Change parameter value using communication.(Function: 05H, 06H, 10H)

- When change the parameter setting value of ' Function setting mode Counter group' or ' Function setting mode Timer group' using communication, reset indication will flash in 3 sec. and display value will be reset. (Counting display value and progress time before changing parameter setting value are not saved.)
- When change the parameter setting value of ' Preset value setting group' or ' Function setting mode Communication group' using communication, counting display value or progress time will not be reset.
- In prohibit writing communication setting ($\Box \Box \overline{\Box} = 1: d \in SR$), a write command does not process.
- If set value beyond the setting range, this setting value is substituted for the value within the setting range and then memorized.

Proper usage

◎ The power ON/OFF



Power voltage rises for 100ms after power on and falls for 500ms after power off. Therefore be sure to apply input signal after 100ms and power turns on again after 500ms when power turns off.

 Be sure to use insulated and resistive voltage /current or Class2 supply power device to input 24VAC/24-48VDC power supply model.

O Input signal line

- Use as short a cable from the sensor to this unit as possible.
- Use shielded cable for long input line.
- Wire as separating input line from the power line.

○ When selecting input logic

Be sure that supply power is off when selecting input logic, then select logic input according to input logic changing method.

O Contact count input (When it is used as Counter)

If apply contact input at high speed mode(1k, 5k, 10k), it may cause miscount by chattering.

Therefore set low speed mode(1cps or 30cps) at contact input.

When test dielectric voltage and insulation resistance of the control panel with this unit installed.

- Please isolate this unit from the circuit of control panel.
- Please make all terminals of this unit short-circuited.

○ Do not use below places.

- Place where there are severe vibration or impact.
- Place where strong alkalis or acids are used.
- Place where there are direct ray of the sun.
- Place where strong magnetic field or electric noise are generated.

○ Installation environment

- It shall be used indoor.
- Altitude Max. 2000m
- Pollution Degree 2
- Installation Category II

(A) Photo electric sensor

(B) Fiber optic sensor

(C) Door/Area

(D) Proximity

(E) Pressure

(F) Rotary encoder

(G) Connector/ Socket

(H) Temp. controller

(I) SSR/

Power controller

(J) Counter

(K) Timer

(L) Panel meter

(M) Tacho/ Speed/ Pulse meter

(N) Display unit

(O) Sensor controller

(P) Switching

mode powe supply

(Q) Stepper motor& Driver&Co

(R) Graphic/ Logic panel

(S) Field network device

(T) Software

(U) Other

senso